

Application of Inversive Methods to Euclidean Geometry

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Place a sphere on top of the Euclidean plane so that its south pole S is at the origin. Let N be the north pole. For any point $Q \neq N$ on the sphere, the point P of intersection of the extension of NQ with the plane is called its image under the **stereographic projection** from N .

Of course, it would be tidier if N had an image as well. How would it behave? As Q approaches N from any direction, the projection P “approaches infinity” in the sense of becoming arbitrarily far away from S . If we add a *point at infinity* I to the Euclidean plane, with the property that a sequence (P_j) is defined to converge to I if and only if $|P_j|$ increases without bound, we will have what is known as the **inversive plane**. Think of the sphere as a balloon and the point N as a puncture. If we stretch the balloon out onto the plane, we can see that the point I is in every direction!

We define the point I to be the projection of N . It is called the **ideal point**, and lies on every straight line. To see this, consider a straight line ℓ on the inversive plane and the plane passing through N and ℓ . The cross-section with the sphere is a circle passing through the point N , justifying the statement that I lies on every straight line. In fact, it closes the straight line into something like a circle.

Inversion

For any circle Σ with center O and radius R , and any point $A \neq O, I$, we define the *inverse point of A with respect to Σ* to be the point on the ray \overrightarrow{OA} at distance $R^2/|OA|$ from O . This is readily seen to be an involution (self-inverse map). The points O and I are defined to invert into each other. We consider straight lines to be “circles passing through I ”. Inversion in a straight line is defined to be reflection: the point I is fixed under reflections. The geometry resulting from (and preserved by) these mappings is called *inversive geometry*. For a full introduction to inversive geometry, the reader is referred to any good undergraduate geometry textbook, such as Pedoe [1] (chapter VI) or Baragar [2] (chapter 7).

Exercise 1 *Inversion fixes exactly the points of Σ . It maps points inside Σ to points outside Σ and vice versa.*

The next result is a very useful lemma. Note the order in which the points of the triangles are specified - this is important!

Exercise 2 *Let P, Q , and the center of inversion O not be collinear, and let P, Q invert to P', Q' . Then the triangles $\triangle OPQ$ and $\triangle OQ'P'$ are similar.*

The reflection of a circle in a line is always a circle. Something similar is true for inversions.

Exercise 3 *Inversion maps circles not passing through O to circles, circles passing through O to straight lines not through O , straight lines passing through O to themselves, and other straight lines to circles.*

We can define the angle between two circles, or between a circle and a line, at a point P to be the angle between the tangent lines. Reflection preserves these, of course — so does inversion.

Exercise 4 *Show that inversion preserves angles, whether between two lines, a line and a circle, or two circles.*

Reflection in a line L maps any line or circle that is orthogonal to L to itself. (Note that if a circle meets a line or another circle twice, it makes the same angle at each intersection point. Thus “orthogonal” is well defined here and in the following exercise.)

Exercise 5 *Show that inversion maps any circle orthogonal to Σ to itself.*

Exercise 6 *If a circle C cuts Σ , so does its inverse. If a circle C is tangent to Σ , so is its inverse. If a circle C contains O in its interior, so does its inverse.*

Exercise 7 *The Euclidean construction for an inverse point is simple enough to find by trial and error.*

(i) *Given O and Σ , and a point P inside Σ , construct the inverse point P' .*

(ii) *Given O and Σ , and a point P outside Σ , construct the inverse point P' .*

Reflection preserves reflections: that is, a mirror seen in a mirror acts like a mirror. Something similar holds for inversions:

Exercise 8 *If P and P' are inverse with respect to C , and their inverses with respect to Σ are \bar{P}, \bar{P}' , and \bar{C} respectively, then \bar{P} and \bar{P}' are inverses with respect to \bar{C} .*

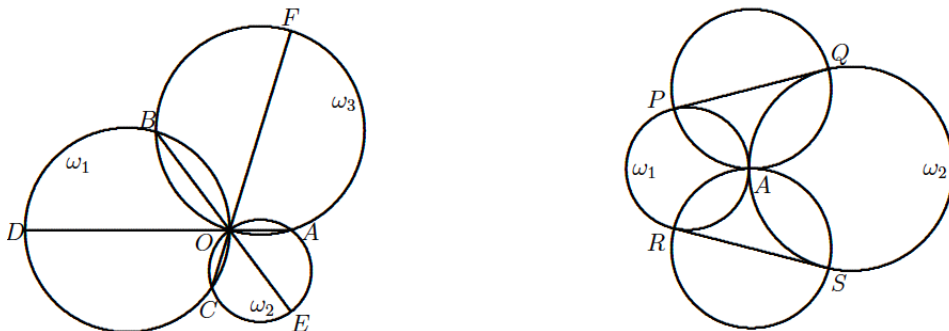
We might wonder if inversion preserves circle centers, but it doesn't. (It's easy to find a counterexample — find one!) There is a way to find the center of an inverse circle, though.

Exercise 9 *If C and \bar{C} are inverses with respect to Σ , then the center A of \bar{C} is found as follows. Let B be the inverse of O in C ; then A is the inverse of B in Σ .*

Problems

Problem 1 (below left)

Three circles ω_1 , ω_2 and ω_3 pass through O . C is the other point of intersection of ω_1 and ω_2 , A is the other point of intersection of ω_2 and ω_3 , and B is the other point of intersection of ω_3 and ω_1 . The extension of AO intersects ω_1 again at D , the extension of BO intersects ω_2 again at E , and the extension of CO intersects ω_3 again at F . Prove that if OE and OF are diameters of ω_2 and ω_3 respectively, then OD is a diameter of ω_1 .

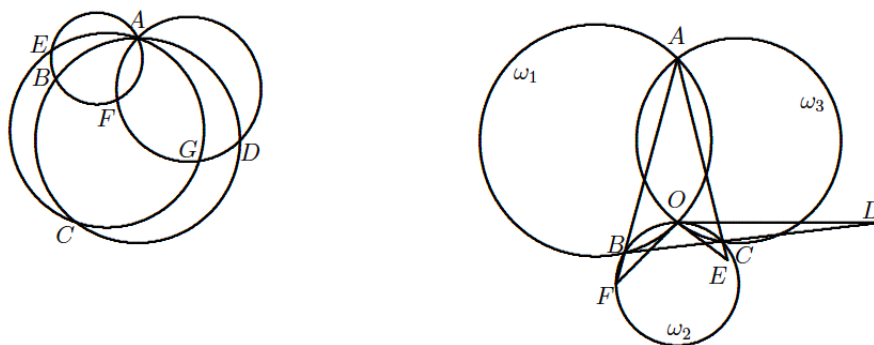


Problem 2 (above right)

Two circles ω_1 and ω_2 are tangent externally to each other at A . A common exterior tangent touches ω_1 at P and ω_2 at Q . The other common exterior tangent touches ω_1 at R and ω_2 at S . Prove that the circumcircles of triangles PAQ and RAS are tangent to each other.

Problem 3 (below left)

AB , AC and AD are three chords on a circle. Circles with AB and AC as diameters intersect at E , circles with AB and AD as diameters intersect at F , and circles with diameters AC and AD intersect at G . Prove that E , F and G are collinear.

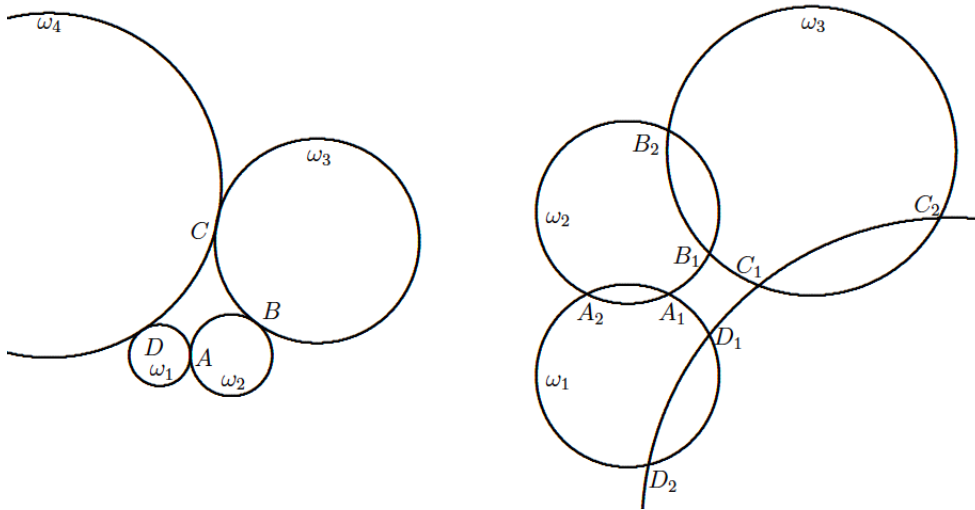


Problem 4 (above right)

Three circles ω_1 , ω_2 and ω_3 pass through O . B is the other point of intersection of ω_1 and ω_2 , C is the other point of intersection of ω_2 and ω_3 , and A is the other point of intersection of ω_3 and ω_1 . The tangent to ω_2 at O intersects BC at D , the tangent at O to ω_3 intersects CA at E , and the tangent at O to ω_1 intersects AB at F . Prove that D , E and F are collinear.

Problem 5 (below left)

Four circles ω_1 , ω_2 , ω_3 and ω_4 are such that ω_1 and ω_2 touch at A , ω_2 and ω_3 touch at B , ω_3 and ω_4 touch at C and ω_4 and ω_1 touch at D . Prove that A , B , C and D are concyclic.

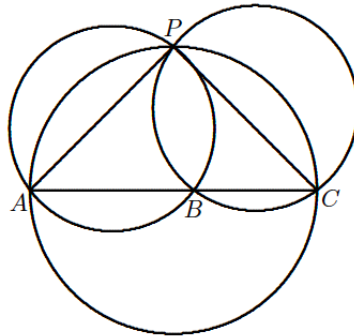


Problem 6 (above right)

Four circles $\omega_1, \omega_2, \omega_3$ and ω_4 are such that ω_1 and ω_2 intersect at A_1 and A_2 , ω_2 and ω_3 intersect at B_1 and B_2 , ω_3 and ω_4 intersect at C_1 and C_2 , and ω_4 and ω_1 intersect at D_1 and D_2 . Prove that if A_1, B_1, C_1 and D_1 are collinear or concyclic, then so are A_2, B_2, C_2 and D_2 .

Problem 7 (below)

A, B and C are three points on a line and P is a point not on this line. Prove that the circumcentres of triangles PAB, PBC and PCA are concyclic with P .



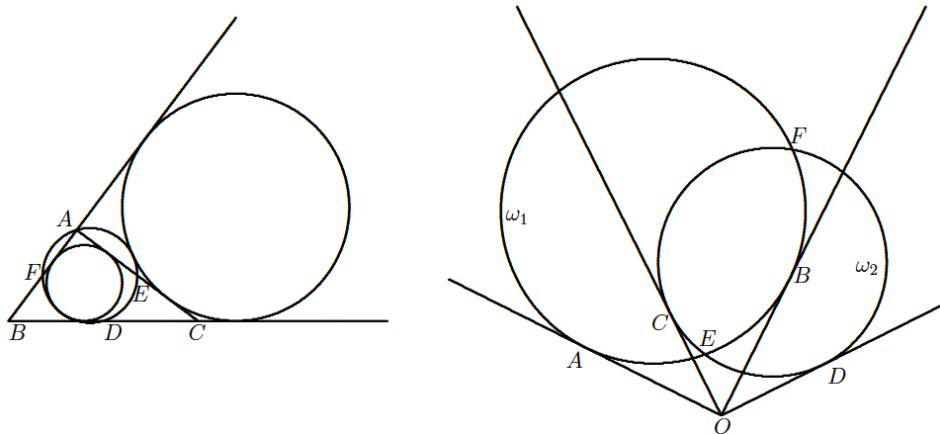
Problem 8

Prove Ptolemy’s Inequality which states that $AB \cdot CD + AD \cdot BC \geq AC \cdot BD$ for any convex quadrilateral $ABCD$, with equality if and only if the quadrilateral is cyclic. (Hint: Because this is quantitative, expect to use the “polar-coordinate” definition of inversion.)

Problem 9 (below left)

Prove that the circle which passes through the midpoints of the sides of a triangle

is tangent to the triangle's incircle and excircles.

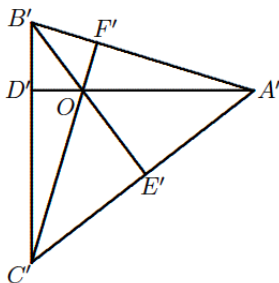


Problem 10 (above right)

From a point O are four rays OA , OC , OB and OD in that order, such that $\angle AOB = \angle COD$. A circle tangent to OA and OB intersects a circle tangent to OC and OD at E and F . Prove that $\angle AOE = \angle DOF$.

The solution to Problem 1 is given as an example. We leave the others to the reader!

Solution (to Problem 1) Invert with respect to any circle with center O . Then the three circles turn into triangle $A'B'C'$ while the radial lines OA , OB and OC invert to themselves. That OE is a diameter of ω_2 means that $B'E'$ is orthogonal to $A'C'$. Similarly, $C'F'$ is orthogonal to $A'B'$. Hence O is the orthocentre of triangle $A'B'C'$, so that $A'O$ is orthogonal to $B'C'$. It follows that OD is indeed a diameter of ω_1 .



References

- [1] Baragar, A., *A Survey of Classical and Modern Geometries*, Pearson, 2001.
- [2] Pedoe, D., *Geometry: A Comprehensive Course*, Dover, 1970.

