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Continuation of Point Clouds via Persistence Diagrams

We present a mathematical and algorithmic framework for the continuation of point clouds via persistence diagrams. We show that the persistence map, which assigns a persistence diagram to a point cloud, is differentiable. This allows us to apply the Newton-Raphson continuation method in this setting. Given an initial point cloud P and its corresponding persistence diagram PD , we apply continuation to find a new point cloud P' close to P , that have a prescribed persistence diagram PD' close to PD . We present algorithms to perform the continuation as well as some computational results. This is joint work with Yasuaki Hiraoka (WPI-AIMR, Tohoku University) and Ippei Obayashi (WPI-AIMR, Tohoku University).